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The following program code generates the approximated tail lower bound distribution of the QLR test statistic given in the paper, Testing for Regime Switching by Cho, JS and White, H.

The first step to obtain this bound is to compute

$$\int_{\Theta} \gamma(\theta) d\theta$$

We compute this by the numerical integration method, and next obtain the desired lower bound by Theorem 8. The following four different cases are those considered in Table 1.

Case 1: When the variance term is known, and the null parameter value is at the center of the parameter space.

The matrix "ttc" given below provides the desired lower bound. The first column of "ttc" represent the percentile, and the other columns are the quantiles corresponding to the various parameter spaces considered in the paper. For example, ttc[:,2] provides the tail lower bound when the parameter space is [-1, 1].

Case 2: When the variance term is known, and the null parameter value is at the corner of the parameter space.

The matrix "ttc0" given below provides the desired lower bound. The first column of "ttc0" represents the percentile, and the other columns are the quantiles corresponding to the various parameter spaces considered in the paper. For example, ttc0[:,2] provides the tail lower bound when the parameter space is [0, 1].

Case 3: When the variance term is unknown, and the null parameter value is at the center of the parameter space.

The matrix "ttd" given below provides the desired lower bound. The first column of "ttd" represents the percentile, and the other columns are the quantiles corresponding to the various parameter spaces considered in the paper. For example, ttd[:,2] provides the tail lower bound when the parameter space is [-1, 1].

Case 4: When the variance term is unknown, and the null parameter value is at the corner of the parameter space.

The matrix "ttd0" given below provides the desired lower bound. The first column of

"ttd0" represents the percentile, and the other columns are the quantiles corresponding to the various parameter spaces considered in the paper. For example, ttd0[:,2] provides the tail lower bound when the parameter space is [0, 1].

Comment: Researchers can modify the parameter space, and also they need to modify the functional form of $\gamma(\theta)$ if they consider different mixture distributions.

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*/
new;
library pgraph;

_intord = 40;

proc rc11(x);
    retp(sqrt( (1+exp(2*x^2)-exp(x^2)).*(2+x^4))./(1-exp(x^2)+x^2)^2 ));
endp;

proc rd11(x);
    retp(sqrt( 2*(2+2*exp(2*x^2)+4*x^2+x^4-exp(x^2)).*(4+4*x^2-x^4+x^6))
            ./((2-2*exp(x^2)+2*x^2+x^4)^2 )));
endp;

uuu = seqa(0, 10/10000, 10001);
ttc = zeros(10001,6);
ttc0= zeros(10001,6);
ttd = zeros(10001,6);
ttd0= zeros(10001,6);

/* parameter space [-1, 1] */
x11 = 1|-1;

/* parameter space [-2, 2] */
x22 = 2|-2;

/* parameter space [-3, 3] */
x33 = 3|-3;

/* parameter space [-4, 4] */
x44 = 4|-4;

/* parameter space [-5, 5] */
x55 = 5|-5;

c11 = intquad1(&rc11, x11);
d11 = intquad1(&rd11, x11);
c01 = c11/2;
d01 = d11/2;

c22 = intquad1(&rc11, x22);
d22 = intquad1(&rd11, x22);
c02 = c22/2;
d02 = d22/2;

c33 = intquad1(&rc11, x33);

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d33 = intquad1(&rd11, x33);
c03 = c33/2;
d03 = d33/2;

c44 = intquad1(&rc11, x44);
d44 = intquad1(&rd11, x44);
c04 = c44/2;
d04 = d44/2;

c55 = intquad1(&rc11, x55);
d55 = intquad1(&rd11, x55);
c05 = c55/2;
d05 = d55/2;

iii = 1;
do until iii > 10001;
    ttc[iii,1] = sqrt(uuu[iii,1]);
    ttc[iii,2] = 1 - 2*( pdfn(ttc[iii,1])*c01/sqrt(2*pi) + (1-cdfn(ttc[iii,1]))
);
    ttc[iii,3] = 1 - 2*( pdfn(ttc[iii,1])*c02/sqrt(2*pi) + (1-cdfn(ttc[iii,1]))
);
    ttc[iii,4] = 1 - 2*( pdfn(ttc[iii,1])*c03/sqrt(2*pi) + (1-cdfn(ttc[iii,1]))
);
    ttc[iii,5] = 1 - 2*( pdfn(ttc[iii,1])*c04/sqrt(2*pi) + (1-cdfn(ttc[iii,1]))
);
    ttc[iii,6] = 1 - 2*( pdfn(ttc[iii,1])*c05/sqrt(2*pi) + (1-cdfn(ttc[iii,1]))
);

    ttc0[iii,1] = sqrt(uuu[iii,1]);
    ttc0[iii,2] = 1 - ( pdfn(ttc0[iii,1])*c01/sqrt(2*pi)+(1-cdfn(ttc0[iii,1]))
);
    ttc0[iii,3] = 1 - ( pdfn(ttc0[iii,1])*c02/sqrt(2*pi)+(1-cdfn(ttc0[iii,1]))
);
    ttc0[iii,4] = 1 - ( pdfn(ttc0[iii,1])*c03/sqrt(2*pi)+(1-cdfn(ttc0[iii,1]))
);
    ttc0[iii,5] = 1 - ( pdfn(ttc0[iii,1])*c04/sqrt(2*pi)+(1-cdfn(ttc0[iii,1]))
);
    ttc0[iii,6] = 1 - ( pdfn(ttc0[iii,1])*c05/sqrt(2*pi)+(1-cdfn(ttc0[iii,1]))
);

    ttd[iii,1] = sqrt(uuu[iii,1]);
    ttd[iii,2] = 1 - 2*( pdfn(ttd[iii,1])*d01/sqrt(2*pi)+(1-cdfn(ttd[iii,1])) )
- (1-cdfn(ttd[iii,1]));
    ttd[iii,3] = 1 - 2*( pdfn(ttd[iii,1])*d02/sqrt(2*pi)+(1-cdfn(ttd[iii,1])) )
- (1-cdfn(ttd[iii,1]));
    ttd[iii,4] = 1 - 2*( pdfn(ttd[iii,1])*d03/sqrt(2*pi)+(1-cdfn(ttd[iii,1])) )
- (1-cdfn(ttd[iii,1]));
    ttd[iii,5] = 1 - 2*( pdfn(ttd[iii,1])*d04/sqrt(2*pi)+(1-cdfn(ttd[iii,1])) )
- (1-cdfn(ttd[iii,1]));
    ttd[iii,6] = 1 - 2*( pdfn(ttd[iii,1])*d05/sqrt(2*pi)+(1-cdfn(ttd[iii,1])) )
- (1-cdfn(ttd[iii,1]));

    ttd0[iii,1] = sqrt(uuu[iii,1]);
    ttd0[iii,2] = 1 - ( pdfn(ttd0[iii,1])*d01/sqrt(2*pi)+(1-cdfn(ttd0[iii,1])) )
- (1-cdfn(ttd0[iii,1]));
    ttd0[iii,3] = 1 - ( pdfn(ttd0[iii,1])*d02/sqrt(2*pi)+(1-cdfn(ttd0[iii,1])) )
- (1-cdfn(ttd0[iii,1]));

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    ttd0[iii,4] = 1 - ( pdfn(ttd0[iii,1])*d03/sqrt(2*pi)+(1-cdfn(ttd0[iii,1])) )
- (1-cdfn(ttd0[iii,1]));
    ttd0[iii,5] = 1 - ( pdfn(ttd0[iii,1])*d04/sqrt(2*pi)+(1-cdfn(ttd0[iii,1])) )
- (1-cdfn(ttd0[iii,1]));
    ttd0[iii,6] = 1 - ( pdfn(ttd0[iii,1])*d05/sqrt(2*pi)+(1-cdfn(ttd0[iii,1])) )
- (1-cdfn(ttd0[iii,1]));

    iii = iii + 1;
endo;

print "Case 1";
print uu~ttc[.,2:6];

print "Case 2";
print uu~ttc0[.,2:6];

print "Case 3";
print uu~ttd[.,2:6];

print "Case 4";
print uu~ttd0[.,2:6];
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